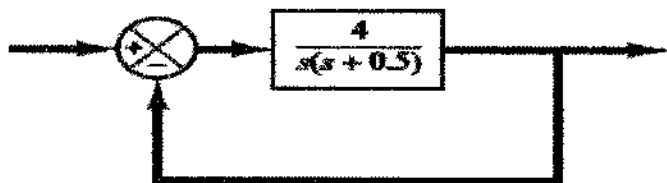




**Answer all the following questions:**

**Problem 1: (30 Marks)**

- Compare between lead and lag compensators? (10 Marks)
- Consider the control system shown in following figure



**Figure 1**

The damping ratio is 0.125, the undamped natural frequency is 2 rad/sec, and the static velocity error constant is 8 sec<sup>-1</sup>. It is desired to make the damping ratio of the dominant closed-loop poles equal to 0.5 and to increase the undamped natural frequency to 5 rad/sec and the static velocity error constant to 80 sec<sup>-1</sup>. Design an appropriate compensator to meet all the performance specifications. (20 Marks)

**Problem 2: (30 Marks)**

- Define gain margin, phase margin and explain graphically. What are the gain margin and the phase margin indicate? (12 Marks)
- Construct the polar plot for the function  $GH(S) = 2(S+1)/S^2$ . Find Gain cross over frequency, Phase cross over frequency, Gain margin and Phase margin. (18 Marks).

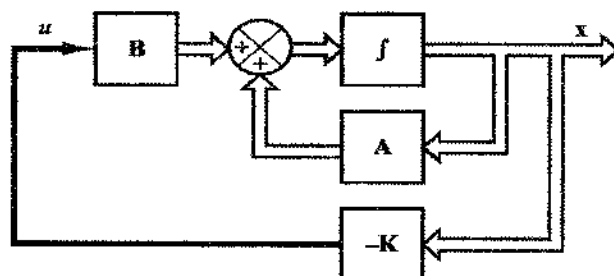
**Problem 3: (30 Marks)**

- Draw the bode plot of the system and Comment on the stability of the system. (10 Marks)

$$G(s) = \frac{K(s + 3)}{s(s + 1)(s + 2)}$$

- For the following transfer function:  $G(s) = \frac{Y(s)}{U(s)} = \frac{s^2 + 7s + 2}{s^3 + 9s^2 + 26s + 24}$ . Draw the simulation diagram and find the state space representation for the above transfer function. (10 Marks)
- Consider the regulator system shown in following Figure 2. The plant is given by: (10 Marks)

$$\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \\ \dot{x}_3 \end{bmatrix} = \begin{bmatrix} 1 & 2 & 1 \\ 0 & 1 & 3 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} + \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} u(t)$$



**Figure 2**

Determine the state feedback gain for each state variable to place the poles at  $-1+j$ ,  $-1-j$ ,  $-3$ .