

1- True or False [10 points]

- a) The searching algorithm is optimal if it is able to find the goal at the optimal path with respect to the frontiers selection criteria. (T)
- b) Breadth first search is an optimal algorithm. (T)
- c) Depth first search is an optimal algorithm. (F)
- d) Uniform-cost search is a complete searching algorithm. (T)
- e) If variable B depends on variable A then $P(A|B)=1-P(A|B)$. (F)

2- Choose the correct answer [10 points]

1- Which instruments are used for perceiving and acting upon the environment?

- a) Sensors and Actuators
- b) Sensors
- c) Perceiver
- d) None of the mentioned

2- What is Artificial intelligence?

- a) Putting your intelligence into Computer
- b) Programming with your own intelligence
- c) Making a Machine intelligent
- d) Playing a Game
- e) Putting more memory into Computer

3- Artificial Intelligence has its expansion in the following application.

- a) Planning and Scheduling
- b) Game Playing
- c) Diagnosis
- d) Robotics
- e) All of the above

4- Categorize Crossword puzzle in Fully Observable / Partially Observable.

- a) Fully Observable
- b) partially Observable

5- What is state space?

- a) The whole problem
- b) Your Definition to a problem
- c) Problem you design
- d) Representing your problem with variable and parameter
- e) A space where you know the solution

3- Answer the following questions [20 points]

1- What are the different approaches in defining artificial intelligence?[5]

- Thinking rationally
- Acting rationally
- Thinking like a human
- Acting like a human

2- Define: [5]

An agent. An agent is anything that can be viewed as perceiving its environment through sensors and executing actions using actuators.

Intelligence:

- What we understand as intelligence in humans.
- The ability to bring all the knowledge a system has at its disposal to bear in the solution of a problem.
- A more practical definition that has been used in the context of building artificial systems with intelligence is to perform better on tasks that humans currently do better.

3- What is the advantage of using A* compared with uniform cost.[5]

The advantages of using A* compared to uniform cost:

- ① Uniform Cost search is a special case of A* search
 $A^* : f = g + h$, uniform $f = g$
- ② A* is admissible
- ③ A* is complete and optimally efficient for a given heuristic.

4- An economics consulting firm has created a model to predict recessions. The model predicts a recession with probability 80% when a recession is indeed coming and with probability 10% when no recession is coming. The unconditional probability of falling into a recession is 20%. If the model predicts a recession, what is the probability that a recession will indeed come?[5]

recessions	رکود	تصرفات
recessions predict	B	وقوع رکود
recessions coming	A	علائم رکود

Given • $P(B/A) = 0.8$

• $P(B/\neg A) = 0.1$

unconditional probability of falling into recessions

• $P(A) = 0.2 \Rightarrow P(\neg A) = 0.8$

$P(A/B) ??$

From total probability

$$P(B) = P(B/A) * P(A) + P(B/\neg A) * P(\neg A)$$

$$= 0.8 * 0.2 + 0.1 * 0.8 = 0.24$$

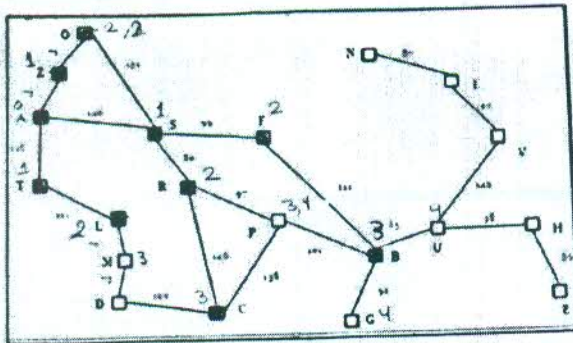
Bayes' rule

$$P(A/B) = \frac{P(A) * P(B/A)}{P(B)}$$

$$\Rightarrow \frac{0.2 * 0.8}{0.24} = 0.6666$$

4- Answer by explanations and drawing [20 points]

1- Use breadth first search to find the path between A and C and give its path. [10]



BFS

A → C

step 0:

A at level 0

A is not the goal
expand A

step 1: A → Z, A → S, A → T (Level 1)

step 2: at A → Z, Z is not the goal expand Z

Z → O (Level 2)

step 3: at A → S, S is not the goal expand S

S → F, S → R, S → O (Level 2)

step 4: at A → T, T is not the goal expand T

T → L (Level 2)

step 5: at Z → O, O is not the goal expand O
No paths from O

step 6: at S → F, F is not the goal expand F

F → B (Level 3)

step 7: at S → R, R is not the goal expand R

R → P, R → C (Level 3)

step 8: at T → L, L is not goal expand L

L → M (Level 3)

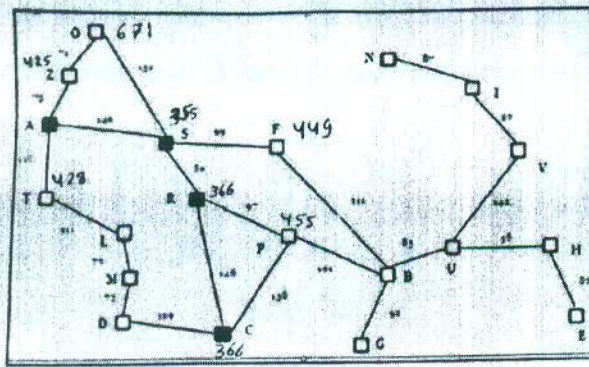
step 9: at F → B, B is not the goal expand B

B → G, B → U, B → P (Level 4)

step 10: at R → C, C is the goal expand C

The path is A → S → R → C

2- Use A* search to find the path between A and C and give its path, and cost. [10]



A^*
 $A \rightarrow C$

step 1 A is not the goal expand A

step 2 $A \xrightarrow{425} Z$, $A \xrightarrow{355} S$, $A \xrightarrow{428} T$

step 3 cheapest at S
 S is not the goal expand S

$S \xrightarrow{449} F$, $S \xrightarrow{366} R$, $S \xrightarrow{671} O$

step 4 cheapest at R
 R is not the goal expand R

$R \xrightarrow{455} P$, $R \xrightarrow{366} C$

step 5 : cheapest at C

C is the goal expand C

The path is $A \rightarrow S \rightarrow R \rightarrow C$

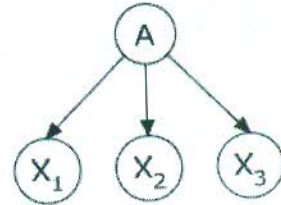
the cost 366

5- Answer by explanations [15 points]

Consider the following network, where the $P(A) = 0.5$, $\forall i P(X_i|A) = 0.2$, $P(X_i|\neg A) = 0.6$.

Calculate

- 1- $P(A|X_1, X_2, X_3)$ [8]
- 2- $P(X_3|X_1)$ [7]



(5)

$$P(A) = 0.5 \quad \forall i P(X_i|A) = 0.2 \quad P(X_i|\neg A) = 0.6$$

$$P(A|X_1, X_2, X_3)$$

By using Normalize P^i

$P(\cdot)$	$P(X_1 \cdot)$	$P(X_2 \cdot)$	$P(X_3 \cdot)$	P^i
A	0.5	0.2	0.2	0.004
$\neg A$	0.5	0.6	0.6	0.108

$$P(A) = 0.5 \quad P(\neg A) = 0.5$$

$$P(X_i|A) = 0.2$$

$$P(\neg X_i|A) = 0.8$$

$$P(X_i|\neg A) = 0.6$$

$$P(\neg X_i|\neg A) = 0.4$$

$$Z = 0.004 + 0.108 = 0.112$$

$$Z^{-1} = 8.92$$

$$P(A|X_1, X_2, X_3) = Z^{-1} P^i(A|X_1, X_2, X_3)$$

$$= 8.92 \times 0.004 = \boxed{0.035714}$$

$$P(X_3|X_1)$$

$$= P(A|X_1) \cdot P(X_3|A) + P(\neg A|X_1) \cdot P(X_3|\neg A)$$

$$= 0.1 \times 2.5 \times 0.2 + 0.3 \times 2.5 \times 0.6$$

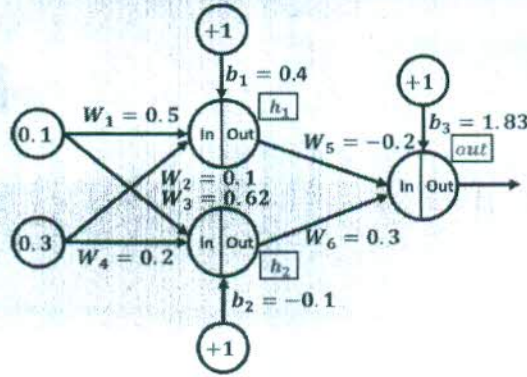
$$= 0.5$$

$P(A X_1)$	$P(\cdot)$	$P(X_3 \cdot)$	$P^i(\cdot)$	$P(\cdot X_1)$
A	0.5	0.2	0.1	0.25
$\neg A$	0.5	0.6	0.3	0.75

$$Z^{-1} = 2.5$$

$$\boxed{P(X_3|X_1) = 0.5}$$

6- Answer by complete calculation [15 points]



$$h_{1in} = X_1 * W_1 + X_2 * W_2 + b_1 = 0.1 * 0.5 + 0.3 * 0.1 + 0.4$$

$$h_{1in} = 0.48$$

$$h_{1out} = \frac{1}{1 + e^{-h_{1in}}} = \frac{1}{1 + e^{-0.48}}$$

$$h_{1out} = 0.618$$

$$h_{2in} = X_1 * W_3 + X_2 * W_4 + b_2 = 0.1 * 0.62 + 0.3 * 0.2 - 0.1$$

$$h_{2in} = 0.022$$

$$h_{2out} = \frac{1}{1 + e^{-h_{2in}}} = \frac{1}{1 + e^{-0.022}}$$

$$h_{2out} = 0.506$$

$$out_{in} = h_{1out} * W_5 + h_{2out} * W_6 + b_3 = 0.618 * -0.2 + 0.506 * 0.3 + 1.83$$

$$out_{in} = 1.858$$

$$out_{out} = \frac{1}{1 + e^{-out_{in}}} = \frac{1}{1 + e^{-1.858}}$$

$$out_{out} = 0.865$$

desired = 0.03 Predicted = out_{out} = 0.865

$$E = \frac{1}{2} (desired - out_{out})^2 = \frac{1}{2} (0.03 - 0.865)^2$$

$$E = 0.349$$

Need to calculate

Backward

$\frac{\partial E}{\partial W_1'}$	$\frac{\partial E}{\partial W_2'}$	$\frac{\partial E}{\partial W_3'}$	$\frac{\partial E}{\partial W_4'}$	$\frac{\partial E}{\partial W_5'}$	$\frac{\partial E}{\partial W_6}$
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$$\frac{\partial E}{\partial W_5} = \frac{\partial E}{\partial out_{out}} * \frac{\partial out_{out}}{\partial out_{in}} * \frac{\partial out_{in}}{\partial W_5}$$

$$\frac{\partial E}{\partial out_{out}} = \frac{\partial}{\partial out_{out}} \left(\frac{1}{2} (desired - out_{out})^2 \right)$$

$$\frac{\partial E}{\partial out_{out}} = out_{out} - desired$$

$$\frac{\partial out_{out}}{\partial out_{in}} = \frac{\partial}{\partial out_{in}} \left(\frac{1}{1 + e^{-out_{in}}} \right) \quad \frac{\partial out_{out}}{\partial out_{in}} = \left(\frac{1}{1 + e^{-out_{in}}} \right) \left(1 - \frac{1}{1 + e^{-out_{in}}} \right)$$

$$\frac{\partial out_{out}}{\partial out_{in}} = \left(\frac{1}{1 + e^{-1.858}} \right) \left(1 - \frac{1}{1 + e^{-1.858}} \right) = \left(\frac{1}{1.56} \right) \left(1 - \frac{1}{1.56} \right)$$

$$= (0.641)(1 - 0.641) = (0.641)(0.359) \quad \boxed{\frac{\partial out_{out}}{\partial out_{in}} = 0.23}$$

$$\frac{\partial out_{in}}{\partial W_5} = \frac{\partial}{\partial W_5} (h_{1out} * W_5 + h_{2out} * W_6 + b_3) = 1 * h_{1out} * (W_5)^{1-1} + 0 + 0$$

$$\frac{\partial out_{in}}{\partial W_5} = h_{1out} \quad \boxed{\frac{\partial out_{in}}{\partial W_5} = 0.618}$$

$$\frac{\partial E}{\partial W_5} = 0.835 * 0.23 * 0.618 \quad \boxed{\frac{\partial E}{\partial W_5} = 0.119}$$

$$\frac{\partial E}{\partial W_6} = \frac{\partial E}{\partial out_{out}} * \frac{\partial out_{out}}{\partial out_{in}} * \frac{\partial out_{in}}{\partial W_6}$$

$$\frac{\partial E}{\partial out_{out}} = 0.835 \quad \frac{\partial out_{out}}{\partial out_{in}} = 0.23$$

$$\frac{\partial out_{in}}{\partial W_6} = \frac{\partial}{\partial W_6} (h_{1out} * W_5 + h_{2out} * W_6 + b_3) = 0 + 1 * h_{2out} * (W_6)^{1-1} + 0$$

$$\frac{\partial out_{in}}{\partial W_6} = h_{2out} \quad \boxed{\frac{\partial out_{in}}{\partial W_6} = 0.506}$$

$$\frac{\partial E}{\partial W_6} = 0.835 * 0.23 * 0.506 \quad \boxed{\frac{\partial E}{\partial W_6} = 0.097}$$

$$\frac{\partial E}{\partial W_1} = \frac{\partial E}{\partial out_{out}} * \frac{\partial out_{out}}{\partial out_{in}} * \frac{\partial out_{in}}{\partial h_{1out}} * \frac{\partial h_{1out}}{\partial h_{1in}} * \frac{\partial h_{1in}}{\partial W_1}$$

$$\frac{\partial out_{in}}{\partial h_{1out}} = \frac{\partial}{\partial h_{1out}} (h_{1out} * W_5 + h_{2out} * W_6 + b_3) = (h_{1out})^{1-1} * W_5 + 0 + 0$$

$$\frac{\partial out_{in}}{\partial h_{1out}} = W_5 \quad \boxed{\frac{\partial out_{in}}{\partial h_{1out}} = -0.2}$$

$$\frac{\partial h_{1out}}{\partial h_{1in}} = \frac{\partial}{\partial h_{1in}} \left(\frac{1}{1 + e^{-h_{1in}}} \right) \quad \frac{\partial h_{1out}}{\partial h_{1in}} = \left(\frac{1}{1 + e^{-h_{1in}}} \right) \left(1 - \frac{1}{1 + e^{-h_{1in}}} \right)$$

$$\frac{\partial h_{1in}}{\partial W_1} = \frac{\partial}{\partial W_1} (X_1 * W_1 + X_2 * W_2 + b_1) \quad \frac{\partial h_{1out}}{\partial h_{1in}} = 0.236$$

$$= X_1 * (W_1)^{1-1} + 0 + 0$$

$$\frac{\partial h_{1in}}{\partial W_1} = X_1$$

$$\boxed{\frac{\partial h_{1in}}{\partial W_1} = 0.1}$$

$$\frac{\partial E}{\partial W_1} = 0.835 * 0.23 * -0.2 * 0.236 * 0.1$$

$$\boxed{\frac{\partial E}{\partial W_1} = -0.001}$$

$$\frac{\partial E}{\partial W_2} = \frac{\partial E}{\partial out_{out}} * \frac{\partial out_{out}}{\partial out_{in}} * \frac{\partial out_{in}}{\partial h_{1out}} * \frac{\partial h_{1out}}{\partial h_{1in}} * \frac{\partial h_{1in}}{\partial W_2}$$

$$\frac{\partial h_{1in}}{\partial W_2} = \frac{\partial}{\partial W_2} (X_1 * W_1 + X_2 * W_2 + b_1) = 0 + X_2 * (W_2)^{1-1} + 0$$

$$\frac{\partial h_{1in}}{\partial W_2} = X_2$$

$$\boxed{\frac{\partial h_{1in}}{\partial W_2} = 0.3}$$

$$\frac{\partial E}{\partial W_2} = 0.835 * 0.23 * -0.2 * 0.236 * 0.3$$

$$\boxed{\frac{\partial E}{\partial W_2} = -0.003}$$

$$\frac{\partial E}{\partial W_3} = \frac{\partial E}{\partial out_{out}} * \frac{\partial out_{out}}{\partial out_{in}} * \frac{\partial out_{in}}{\partial h_{2out}} * \frac{\partial h_{2out}}{\partial h_{2in}} * \frac{\partial h_{2in}}{\partial W_3}$$

$$\frac{\partial E}{\partial out_{out}} = 0.835$$

$$\frac{\partial out_{out}}{\partial out_{in}} = 0.23$$

$$\frac{\partial out_{in}}{\partial h_{2out}} = \frac{\partial}{\partial h_{2out}} (h_{1out} * W_5 + h_{2out} * W_6 + b_3)$$

$$= 0 + (h_{2out})^{1-1} * W_6 + 0$$

$$\frac{\partial out_{in}}{\partial h_{2out}} = W_6$$

$$\boxed{\frac{\partial out_{in}}{\partial h_{2out}} = 0.3}$$

$$\frac{\partial h_{2out}}{\partial h_{2in}} = \frac{\partial}{\partial h_{2in}} \left(\frac{1}{1 + e^{-h_{2in}}} \right)$$

$$\frac{\partial h_{2out}}{\partial h_{2in}} = \left(\frac{1}{1 + e^{-h_{2in}}} \right) \left(1 - \frac{1}{1 + e^{-h_{2in}}} \right)$$

$$= \left(\frac{1}{1 + e^{-0.022}} \right) \left(1 - \frac{1}{1 + e^{-0.022}} \right)$$

$$\boxed{\frac{\partial h_{2out}}{\partial h_{2in}} = 0.25}$$

$$\begin{aligned}\frac{\partial h_{2_{in}}}{\partial W_3} &= \frac{\partial}{\partial W_3} (X_1 * W_3 + X_2 * W_4 + b_2) \\ &= X_1 * W_3 + X_2 * W_4 + b_2 \\ &= (X_1)^{1-1} * W_3 + 0 + 0\end{aligned}$$

$$\frac{\partial h_{2_{in}}}{\partial W_3} = W_3$$

$$\frac{\partial h_{2_{in}}}{\partial W_3} = 0.62$$

$$\frac{\partial E}{\partial W_3} = 0.835 * 0.23 * 0.3 * 0.25 * 0.62$$

$$\frac{\partial E}{\partial W_3} = 0.009$$

$$\frac{\partial E}{\partial W_4} = \frac{\partial E}{\partial out_{out}} * \frac{\partial out_{out}}{\partial out_{in}} * \frac{\partial out_{in}}{\partial h_{2_{out}}} * \frac{\partial h_{2_{out}}}{\partial h_{2_{in}}} * \frac{\partial h_{2_{in}}}{\partial W_4}$$

$$\begin{aligned}\frac{\partial h_{2_{in}}}{\partial W_4} &= \frac{\partial}{\partial W_4} (X_1 * W_3 + X_2 * W_4 + b_2) = X_1 * W_3 + X_2 * W_4 + b_2 \\ &= 0 + (X_2)^{1-1} * W_4 + 0\end{aligned}$$

$$\frac{\partial h_{2_{in}}}{\partial W_4} = W_4$$

$$\frac{\partial h_{2_{in}}}{\partial W_4} = 0.2$$

$$\frac{\partial E}{\partial W_4} = 0.835 * 0.23 * 0.3 * 0.25 * 0.2$$

$$\frac{\partial E}{\partial W_4} = 0.003$$

$$\frac{\partial E}{\partial W_1} = -0.001$$

$$\frac{\partial E}{\partial W_2} = -0.003$$

$$\frac{\partial E}{\partial W_3} = 0.009$$

$$\frac{\partial E}{\partial W_4} = 0.003$$

$$\frac{\partial E}{\partial W_5} = 0.119$$

$$\frac{\partial E}{\partial W_6} = 0.097$$

$$W_{1_{new}} = W_1 - \eta * \frac{\partial E}{\partial W_1} = 0.5 - 0.01 * -0.001 = 0.50001$$

$$W_{2_{new}} = W_2 - \eta * \frac{\partial E}{\partial W_2} = 0.1 - 0.01 * -0.003 = 0.10003$$

$$W_{3_{new}} = W_3 - \eta * \frac{\partial E}{\partial W_3} = 0.62 - 0.01 * 0.009 = 0.61991$$

$$W_{4_{new}} = W_4 - \eta * \frac{\partial E}{\partial W_4} = 0.2 - 0.01 * 0.003 = 0.1997$$

$$W_{5_{new}} = W_5 - \eta * \frac{\partial E}{\partial W_5} = -0.2 - 0.01 * 0.618 = -0.20618$$

$$W_{6_{new}} = W_6 - \eta * \frac{\partial E}{\partial W_6} = 0.3 - 0.01 * 0.097 = 0.29903$$