



Answer all the following questions:

Problem 1: (20 Marks)

- What is PID control? Explain the control effects by P, I, and D, respectively. [8 Marks]
- Obtain the transfer functions $X_1(s) / U(s)$ and $X_2(s)/U(s)$ of the mechanical system shown in Fig. 1. [12 Marks]

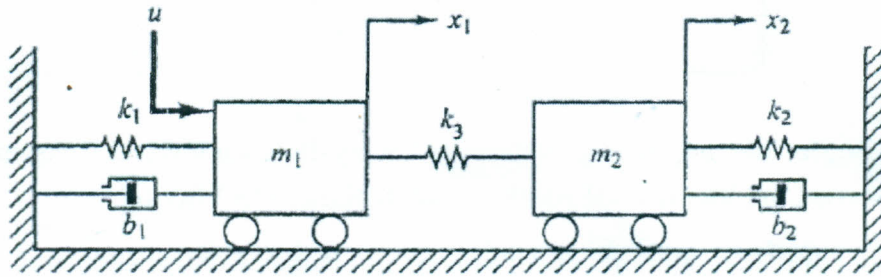


Figure 1

Problem 2: (25 Marks)

- What are the advantages and disadvantages of open-loop and closed-loop control systems? [10 Marks]
- For the system shown in Figure 2, determine the values of gain K and velocity-feedback constant K_h so that the maximum overshoot in the unit-step response is 0.2 and the peak time is 1 sec. With these values of K and K_h , obtain the rise time and settling time. Assume that $J=1 \text{ kg-m}^2$ and $B=1 \text{ N-m/rad/sec}$. [15 Marks]

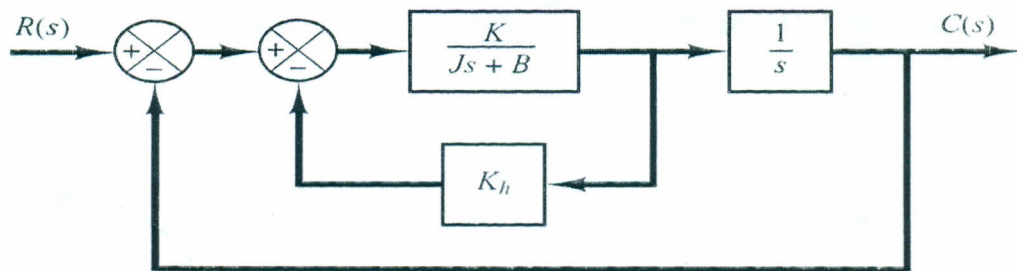


Figure 2

Problem 3: (25 Marks)

- Reduce the block diagram shown below to a single block representing the transfer function, $T(s) = C(s)/R(s)$. [10 Marks]

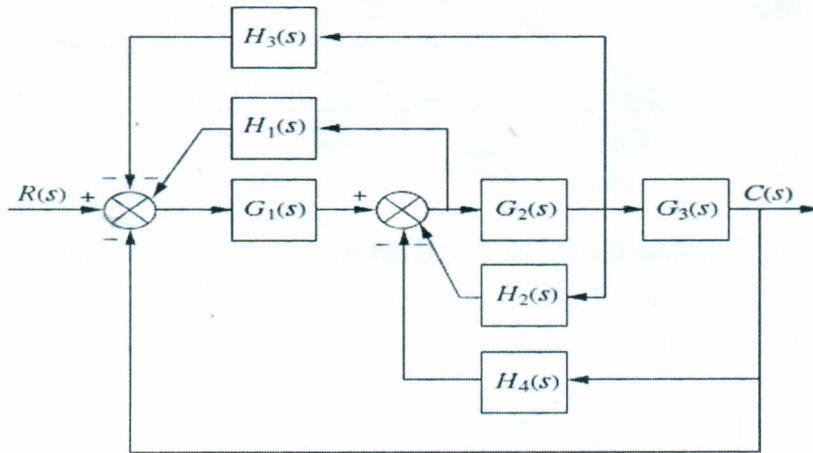


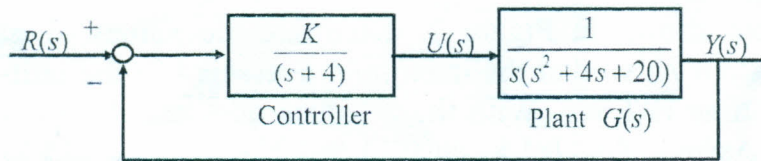
Figure 3

- b) Check whether the following system given by its characteristic equation is stable or not and shows the location of roots on the s-plane. [15 Marks]

$$q(s) = s^5 + s^4 + 2s^3 + 2s^2 + s + 1 = 0$$

Problem 4: (20 Marks)

A feedback control system is proposed. The corresponding block diagram is:



Sketch the root locus of the closed-loop poles as the controller gain K varies from 0 to ∞ .